quantized bound: motor torque max
Priority = 5
torque min
instrument m
Priorit
quantized: motor
Priority = 5
quantized: motor
Priority = 5
INSTRUMENT_PACKAGE_MASS
Priority = 0
Value = 3.0000
IDENTITY-RELATION
Priority = 3
SET:FLIPPER_MOTOR_MASS
Priority = 2
Value = 0.3561
FLIPPER_MOTOR_TORQUE
Priority = 4
Value = 3.5402
IDENTITY-RELATION
Priority = 5
total-mass
Priority = 1
FLIPPER_MOTOR_MASS
Priority = 6
Value = 0.1798
_MOTOR_Y
= 8
Value = 0.0530
quantized: motor
Priority = 5
SET:FLIPPER_MOTOR_TORQUE
Priority = 4
Value = 7.1379
BOT_BODY_MASS
Priority = 2
Value = 8.3991
STRUCTURE_MASS
Priority = 2
Value = 4.5028
R_MOTOR_Z
= 8
Value = 0.0285
component: flipper motor
Y_VO
Priority = 6
Value
TOR_X
ue = 0.0574
FLIPPER_MOTOR_MAX_SPEED
Value = 8.0554
self-righting
Priority = 3
Tetrahedron edge/volume
Priority = 5
FLIPPER_MOTOR_POWER
Priority = 6
Value = 4.4107
Tetrahe
P
BOT_BODY_LENGTH
Priority = 4
Value = 0.2829